Magnetic Wire Traps and Programmable Manipulation of Biological Cells

G. Vieira,1 T. Henighan,1 A. Chen,1 A. J. Hauser,1 F. Y. Yang,1 J. J. Chalmers,2 and R. Sooryakumar1

1Department of Physics, The Ohio State University, Columbus, Ohio 43210, USA
2William G. Lowrie Department of Chemical and Biomolecular Engineering, The Ohio State University, Columbus, Ohio 43210, USA

We present a multiplex method, based on microscopic programmable magnetic traps in zigzag wires patterned on a platform, to simultaneously apply directed forces on multiple fluid-borne cells or biologically inert microparticles or nanoparticles. The gentle tunable forces do not produce damage and retain cell viability. The technique is demonstrated with T-lymphocyte cells remotely manipulated (by a joystick) along desired trajectories on a silicon surface with average speeds up to 20 μm/s.

DOI: 10.1103/PhysRevLett.103.128101 PACS numbers: 87.80.Fe, 75.60.Ch, 83.60.Np, 85.85.+j

Precise manipulation to probe, sort, or assemble individual cells or biomolecules is of great fundamental and practical interest [1–4]. While methods such as those based on atomic force microscopy [5–8], optical tweezers [9–12], and magnetic tweezers [13,14] can manipulate single biological entities with remarkable accuracy, these methods have generally not demonstrated sufficient flexibility and throughput required for widespread adoption. A multiplex approach that would maximize efficiency by applying forces only on targeted individual fluid-borne biological entities will have many advantages. In addition to providing more accurate information than data-averaging a population of cells, such rapid manipulation techniques could also be developed for “on-chip” platforms with small volumes of cell samples at low cost [15]. Dynamic control over picoNewton (pN) scale forces also extends to manipulating inert microparticles and nanoparticles providing, for example, a template to promote large scale self-assembly [16].

In this study we utilize highly localized, permanent magnetic field gradients at the vertices of ferromagnetic zigzag wires patterned on a surface [Fig. 1(a)] to assemble labeled cells or microspheres onto designed arrays. By combining this platform with externally controlled weak (∼60 Oe) fields, cells are transported across surfaces with programmable directed forces that are gentle enough to not produce damage.

The central aspects of this study are demonstrated by remotely manipulating (joystick) individual or multiple T-lymphocyte cells on a silicon surface. The two dimensionality of the platform eases lithographic creation of wire arrays, scale-up to prototypes, and real-time observation with a standard microscope. With symmetries and architecture determined by present nanoscale fabrication techniques, trap arrays with large areal density can be created and integrated into microfluidic devices. The versatility of this approach is further evident when the position of the local magnetic energy minimum is maneuvered away from the wires, and magnetic forces suppress Brownian motion associated with fluid-borne objects.

Figure 1 illustrates key aspects of the platform: a set of zigzag Fe0.9Co0.1 wires with stationary domain walls (DW) [17] located at wire turns [Fig. 1(a) and 1(b)]; the externally applied tuning magnetic fields [Fig. 1(c)]; and magnetic microspheres selectively trapped at the DWs [Fig. 1(d)]. Wires of rectangular cross section were patterned by standard electron-beam writing on a Si substrate followed by sputter deposition of a Fe0.9Co0.1 film and lift-off. Head-to-head (HH) and tail-to-tail (TT) domain walls [Fig. 1(a)] are created at neighboring vertices by a momentary in-plane external field (∼1 kOe) [18]. The localized trapping fields at the wire vertices are evident upon

FIG. 1 (color online). (a) Schematic of a rectangular zigzag wire with a head-to-head (HH) domain wall (DW) at the vertex, associated field \( H_{DW} \), and a trapped magnetic particle (gray circle). (b) Array of zigzag wires patterned on platform with perpendicular \( (H_z) \) and in-plane \( (H_{||}) \) magnetic fields. Sketch in (a) is an enlarged view of the dotted circle around a vertex. (c) Schematic of electromagnets and coil to create \( H_z \) and \( H_{||} \). Cell movement observed by optical microscope (Reichert) with 20X objective lens and high speed camera. (d) Image of superparamagnetic spheres (2.8 μm diameter, dark circles) selectively attracted from solution and trapped only at HH and TT (tail-to-tail) domain walls under no external fields. The FeCo wires patterned on Si are 2 μm wide, 40 nm thick with 16 μm between adjacent vertices.
dispensing a solution of Dynabeads M-280 magnetic microspheres (from Invitrogen) on the platform. As shown in Fig. 1(d) the spheres are attracted to and trapped only at the HH and TT domain walls.

To estimate the strength and tunability of the traps we consider a wire of rectangular cross section with width \( w = 1 \mu \text{m} \) and thickness \( t = 40 \text{ nm} \) supporting a HH wall. For this model we consider the DW to have an associated “magnetic charge” of \( 2\pi r M_s \) [19], where \( M_s \) is the saturation magnetization of \( \text{FeCo}_2 \text{C}_0 \). The magnetic charge is considered to be concentrated at a point yielding an associated magnetic field \( \mathbf{H}_{\text{DW}}(x) \) [19]. Stray fields from other configurations as Bloch walls [20] or domain tips [21] on garnet films have been used for magnetic particle manipulation. Microcoils [22] and permanent magnets [23] have also provided trapping fields. The force \( \mathbf{F} \propto \mathbf{V} (\mathbf{m} \cdot \mathbf{B}) \), where \( \mathbf{m} \) is the magnetic dipole moment of a single superparamagnetic bead in a magnetic field \( \mathbf{B} \). As discussed below, programmable forces relevant to single cell manipulation in the \( 10^{-1} \leq |\mathbf{F}| \leq 10^3 \text{ pN} \) ranges are realized. The net field in the presence of external in-plane \( (\mathbf{H}_\parallel) \) and perpendicular \( (\mathbf{H}_\perp) \) magnetic fields [Fig. 1(b)] is given by \( \mathbf{H} = \mathbf{H}_{\text{DW}} + \mathbf{H}_\parallel + \mathbf{H}_\perp \). For the low values of \( H_{\parallel} \) and \( H_{\perp} \) in this study, the domain walls remain immobile.

Figure 2 reveals noteworthy characteristics of an individual trap and its response to external fields. (i) The \( z \) component of the field gradient above the DW rapidly increases beyond \( 10^4 \text{ T/m} \) in magnitude as the wire surface is approached from above [Fig. 2(a)]. Such high, spatially confined gradients offer a means to manipulate, despite their low volume magnetization, ferromagnetic nanoparticles ranging in size from a few nanometers to 30 nm with pN size forces. Moreover, simulations based on object-oriented micromagnetic framework (OOMMF) program [24] yield a vortex domain wall structure, resulting in field gradients similar to those based on the point charge model. As shown in Fig. 2(a), the two models yield very similar results at 1.4 \( \mu \text{m} \) (radius of microsphere) above the wall, showing our results are essentially independent of the wall model at such heights. (ii) A weak perpendicular external field \( H_z \) (\( \sim 50 \text{ Oe} \)) can augment or diminish the fields near HH and TT walls and thereby tune traps attractive or repulsive—thus targeted objects can be manipulated at tunable distances from the wall [Figs. 2(b)–2(f)]. (iii) The magnitude of \( F_z \) is tunable to hundreds of picoNewtons [Fig. 2(b)], larger than the \( \sim 20 \text{ pN} \) limit for 2.8 \( \mu \text{m} \) diameter particles widely used in magnetic tweezers [25]. (iv) In the absence of \( H_{\parallel} \) and \( H_{\perp} \), \( H_{\text{DW}} \) localizes individual particles at wire vertices [Fig. 2(c)].

Figure 3 and videos in [26] show several transporting examples: either microspheres or T-lymphocyte cells, where previously separated T cells (CD3 positive) from human blood cells [27] were labeled with 1 \( \mu \text{m} \) anti-CD3 spheres. Figures 3(a) and 3(b) show the movement of a microsphere and several T-lymphocyte cells, respectively, above the wire by a sequence of alternating 60 Oe \( H_{\parallel} \) and \( H_{\perp} \) fields. Guided by the wire, the remotely directed forces move these objects with an average speed of 20 \( \mu \text{m/sec} \) from one vertex to the next and beyond by a set of steps as detailed in Fig. 4. The trajectory can be reversed by reordering the sequence of the \( H_{\parallel} \) and \( H_{\perp} \) fields. Figure 3(c) illustrates a T-lymphocyte cell transported away from the wires and returned further down the same wire. Depending on the domain wall (HH or TT), the route and directional forces are regulated by orienting \( H_{\parallel} \) (60 Oe) parallel or antiparallel to the desired planar direction of movement on the platform. Moreover, although the influence of \( H_{\text{DW}} \) diminishes from the wires and Brownian motion of the microspheres becomes clearly noticeable, the fluid-borne microsphere or cell can be held suspended away from the vertex for tens of minutes. Recording \( \langle r^2 \rangle = \langle x^2 + y^2 \rangle \) of the particle using tracking software provides a direct mea-
Figure 3. (a) Sequential applications of planar \( (H_\|) \) and perpendicular \( (H_\perp) \) fields transport (indicated by dots) a microsphere on a Si platform along a zigzag wire. (b) Transport of several T-lymphocyte cells along the wires. The cells (dashed circles in top panel) are conjugated to 1 μm magnetic spheres. (c) Trajectory (white dots) of a single T-lymphocyte cell away from the wires and its controlled return to a neighboring vertex on the same wire. The arrows (and dashed circle in first panel) identify the cell. (d) Simultaneous back and forth transport of five fluid-borne T cells between zigzag wire (1), (2), and (3). Dots identify trajectory of five cells.

Figure 4 underpins the forward motion illustrated in Figs. 3(a) and 3(b) by showing how inverting the energy landscape along the wire assists it. The applicable structure and field geometries are shown in Fig. 4(a). Figures 4(b)–4(f) are calculated magnetic energy profiles for a 2.8 μm diameter bead in the presence of \( H_\| \), \( H_\perp \), \( H_Z \). In Fig. 4(b) the energy minimum is centered above the HH vertex. Upon reversing \( H_\perp \) (while \( H_\| \) remains unchanged), the HH trap at the origin transforms to a repulsive site while moving the energy minimum towards the neighboring TT vertex. The local energy minimum is guided, as shown in Fig. 4(d), towards the TT site by reversing \( H_\| \). Upon alternating the sequence of \( H_\perp \) and \( H_\| \) fields, the cell reaches the TT trap at an average speed of 20 μm/sec. Insets in Figs. 4(b)–4(f) show photographs of the microsphere and their direct correspondence to the mobile energy minimum position.

The two dimensionality of the trap platform (Fig. 1) enables (i) single focal plane for real-time optical observation of single or multiple biological or inert particles trapped and moved on surfaces, (ii) standard lithography of patterned magnetic wires, and (iii) easy manipulation by a joystick or programmed routines via remotely controlled \( H_\| \) and \( H_\perp \) produced by miniature electromagnets. Traditional magnetic tweezers operate in a mode where the motion is perpendicular to the viewing plane, requiring dynamic refocusing or out-of-focus calibrations [13,14]. Further, standard nanoscale lithography allows carefully positioned, ultrahigh field gradients \( >10^4 \) T/m,
Fig. 2(a)] to be applied to nanometer sized magnetic particles which have only limited interference with cell activity. The resulting forces thus offer promising intracellular directed force probe applications [28,29]. For instance, forces greater than 1 pN on 25–50 nm sized iron oxide particles lying within 1 μm above the wires will enable the noncontact planar manipulation of these ultrasmall particles within a cell.

There is also potential for single cell measurements to investigate statistical distributions that would otherwise be obscured by ensemble measurements. Simulations using data with few cells (Fig. 3) support the scale-up to simultaneously perform the experiment on thousands of identical samples. A typical experiment would be to monitor in real time the response of a large number of samples (e.g., ~10^5 cells on a 1 cm × 1 cm platform) to the same stimulus, for example, to measure the consequence of time-resolved optical illumination using a charge-coupled device. Subsequent analysis would produce statistically valid data not only for the average response but also its individual fluctuation spectrum.

Another application of the high array density is their incorporation into microfluidic analytic devices [30,31] to detect small concentration of one species in the midst of other species. An embedded zigzag wire trap array in one microfluid channel can pickoff the magnetically labeled species in the sample flowing in a channel perpendicular to the array channel. Subsequently, a transfer method such as that shown in Fig. 3(b) can move the conjugated species to a separate cross channel where it can be chemically detached and detected. This basic idea can be integrated into existing microfluidic technology as the basis for a new family of on-chip analytic tools.

In conclusion, remotely controlled directed forces from patterned magnetic wires enable the transport of fluid-borne individual or multiple T-lymphocyte cells and microspheres at speeds of several microns per second on a silicon platform. Central to this study are the simple methods to create, with nanoscale precision, highly confined domain wall field gradients. In addition to the convenience of optical microscope observation and advantage of suppressing randomizing thermal fluctuations of fluid-borne cells, development of such mobile magnetic traps will provide real-time analysis of living cells through direct manipulation that offers much more accurate selection than data-averaging over a population of cells.

Support from the National Science Foundation (EEC-0425626), the Army Research Office (W911NF-08-1-0455), and the National Cancer Institute (R01 CA97391-01A1) is acknowledged.


