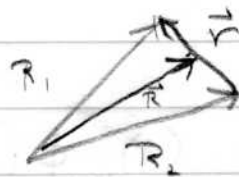


$$H = \frac{p_1^2}{2m_1} + \frac{p_2^2}{2m_2} + V(|\vec{r}_1 - \vec{r}_2|) \leftarrow \text{Galilean symmetries}$$

Center-of-Mass Co-ordinates

$$\vec{R} = (M_1 \vec{R}_1 + M_2 \vec{R}_2) / (M_1 + M_2)$$



$$\vec{r} = \vec{R}_2 - \vec{R}_1$$

$$\vec{P} = \vec{p}_1 + \vec{p}_2, \quad \vec{p} = \frac{m_1 \vec{p}_2 - m_2 \vec{p}_1}{m_1 + m_2}$$

$$H = \frac{P^2}{2M} + \left[\frac{p^2}{2\mu} + V(r) \right] = H_{cm} + H_{rel}$$

$$\mu = \frac{m_1 m_2}{m_1 + m_2} \quad \left. \begin{array}{l} \text{reduced mass} \\ \end{array} \right\} M = m_1 + m_2 \quad \left. \begin{array}{l} \text{total mass} \\ \end{array} \right\}$$

$$\left[\hat{r}_{1i}, \hat{p}_{1j} \right] = \left[\hat{r}_{2i}, \hat{p}_{2j} \right] = i\hbar \delta_{ij}$$

$$\rightarrow \left[\hat{r}_i, \hat{p}_j \right] = \left[\hat{R}_i, \hat{P}_j \right] = i\hbar \delta_{ij}$$

$$\hat{H} = \hat{H}_{cm} + \hat{H}_{rel}$$

$$\hat{H}_{cm} = \frac{\hat{P}^2}{2M}$$

$$H_{rel} = \frac{\hat{p}^2}{2\mu} + V(r)$$

$$|\psi\rangle = |\phi_{\text{cm}}\rangle |\phi_{\text{rel}}\rangle$$

$$\langle \vec{r}_1, \vec{r}_2 | \psi \rangle = \langle \vec{r}, \vec{R} | \psi \rangle = \phi_{\text{cm}}(\vec{R}) \phi_{\text{rel}}(\vec{r})$$

$$\hat{H}_{\text{cm}} |\phi_{\text{cm}}\rangle = E_{\text{cm}} |\phi_{\text{cm}}\rangle$$

$$\hat{H}_{\text{rel}} |\phi_{\text{rel}}\rangle = E_{\text{rel}} |\phi_{\text{rel}}\rangle$$

$$\left\{ \begin{aligned} \frac{\hat{P}^2}{2M} |\phi_{\text{cm}}\rangle &= \frac{\hbar^2 K^2}{2M} |\phi_{\text{cm}}\rangle \\ \phi_{\text{cm}}(\vec{R}) &= \left(\frac{1}{2\pi}\right)^{3/2} e^{i\vec{K}\cdot\vec{R}} \\ &= j_{\ell_c}(KR) Y_{\ell_c}^{m_c}(\theta_c, \varphi_c) \end{aligned} \right.$$

We usually ignore CM wavefunction and work in the CM Frame where $\vec{R}=0$.

$$\text{boosts: } \vec{v} \rightarrow \vec{v} + \vec{v}_0, \quad \vec{x} \rightarrow \vec{x} + \vec{v}_0 t$$

$$\vec{p} \rightarrow \vec{p} + m\vec{v}_0; \quad \vec{P} \rightarrow \vec{P} + M\vec{v}_0, \quad \vec{p} \rightarrow \vec{p}$$

$$\vec{R} \rightarrow \vec{R} + \vec{v}_0 t, \quad \vec{r} \rightarrow \vec{r}$$

We are left with:

rel.
motion

$$\left[\frac{\hat{P}^2}{2\mu} + V(r) \right] \varphi = E \varphi$$

$$\hat{H} \varphi = \left[\frac{\hat{P}_r^2}{2\mu} + \frac{\hat{L}^2}{2\mu r^2} + V(r) \right] \varphi = E \varphi$$

$$\varphi = R(r) Y_l^m(\theta, \phi)$$

$$\left[\frac{\hat{P}_r^2}{2\mu} + \frac{l(l+1)\hbar^2}{2\mu r^2} + V(r) \right] R = ER$$

$$V_{\text{eff}} = V(r) + \frac{l(l+1)\hbar^2}{2\mu r^2}$$

$u(r) = rR$; $u(0) = 0$ - required for solution to Sch., avoids $\delta^3(r)$

$$\hat{P}_r^2 R = -\hbar^2 \frac{1}{r} \frac{\partial^2}{\partial r^2} u$$

$$\left[-\frac{\hbar^2}{2\mu} \frac{\partial^2}{\partial r^2} + V_{\text{eff}}(r) \right] u(r) = E u(r)$$

$$\text{n.o. } V_{\text{eff}}(r) = \frac{1}{2} \mu \omega^2 r^2 + \frac{l(l+1)\hbar^2}{2\mu r^2}$$

$$R_{kl}(r) = \frac{1}{r} u_{kl}(r)$$

$$E_{kl} = \frac{2\mu E_{kl}}{\hbar^2}$$

$$\left[\frac{d^2}{dr^2} - \beta^4 r^2 - \frac{l(l+1)}{r^2} + E_{kl} \right] u_{kl}(r) = 0$$

$$u_{kl}(r) = e^{-\beta r^2/2} y_{kl}(r)$$

$$E_{kl} = \hbar \omega \left(k + l + \frac{3}{2} \right)$$

$$k = 0, 2, 4, \dots$$

produces same degeneracies as $(n_x + n_y + n_z + \frac{3}{2}) \hbar \omega$