

1) $M = \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}$

a) What are M^T and M^\dagger ?

b) What are the eigenvectors and eigenvalues of M ?

c) What is $M^\dagger M$?

d) What is M^{-1} ?

2) A hydrogen atom is in the state:

$$\psi(\vec{r}, 0) = \frac{4}{(2a_0)^{3/2}} \left[\frac{e^{-r/a_0}}{\sqrt{4\pi}} + A \frac{r}{a_0} e^{-r/2a_0} (iY_1^1 - Y_1^0) \right]$$

a) What are the possible measurements of L^2 and what is the probability for each at time t ?

b) What are the possible measurements of L_z and the probabilities for each?

c) At $t = t_0$, L_z is measured and gives 0. What is the expectation value of $D_z = \hat{g} \hat{z}$ for times $t > t_0$?

3) A spin- $\frac{1}{2}$ particle has two eigenstates $|+\rangle$ and $|-\rangle$, where $J^2 |\pm\rangle = \frac{3}{4} \hbar^2 |\pm\rangle$ and $J_z |\pm\rangle = \pm \frac{1}{2} \hbar |\pm\rangle$. At $t=0$ J_y is measured and $\frac{1}{2} \hbar$ is found. What is $|\psi(t)\rangle$ if $H = \omega_0 J_z$? What are the possible measurements of J_x at later times and the probability for each?

4) Two spin- $\frac{1}{2}$ particles have eigenstates $|++\rangle$, $|+-\rangle$, $| -+\rangle$, $| --\rangle$, where $J_i^2 |\psi\rangle = J_2^2 |\psi\rangle = \frac{3}{4} \hbar^2 |\psi\rangle$ for all, $J_{i,z} |\pm, m_i\rangle = \pm \frac{1}{2} \hbar |\pm, m_i\rangle$, $J_{2z} |m_1, \pm\rangle = \pm \frac{1}{2} \hbar |m_1, \pm\rangle$, etc. $H = \frac{J^2}{2I} + \omega_0 J_z$, where $\vec{J} = \vec{J}_1 + \vec{J}_2$. At $t=0$ J_{1z} and J_{2z} are measured and J_{1z} gives $\frac{1}{2} \hbar$ while J_{2z} gives $-\frac{1}{2} \hbar$. What is $|\psi(t)\rangle$?

5) A hydrogen atom is placed in a magnetic field so that $H = H_{\text{Coulomb}} + \omega_0 L_z$ governs the relative motion, with $H_{\text{Coulomb}} = \frac{p_r^2}{2\mu} + \frac{L^2}{2\mu r^2} - \frac{e^2}{r}$.

$$|\psi(0)\rangle = \frac{1}{\sqrt{3}} |211\rangle - \sqrt{\frac{2}{3}} |21-1\rangle$$

What is $|\psi(t)\rangle$? If L_x is measured at time t , what are the possible results and associated probabilities?

6) Rotations about the z-axis are given by:

$$\vec{r}' = \begin{pmatrix} x' \\ y' \end{pmatrix} = \hat{R}(\phi_1) \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos \phi_1 & \sin \phi_1 \\ -\sin \phi_1 & \cos \phi_1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

a) What are $\hat{R}^{-1}(\phi_1)$ and $\hat{R}^+(\phi_1)$?

b) If $\psi = \begin{pmatrix} a \\ b \end{pmatrix}$ what is $\langle \psi | \psi \rangle$? What is ψ' ? What is $\langle \psi' | \psi' \rangle$?

c) Show that $\hat{R}(\phi_2) \hat{R}(\phi_1) = \hat{R}(\phi_1 + \phi_2)$.