

Physics 336K: Newtonian Dynamics
Homework 1: Solutions

2.1. When N point particles interact via gravity the two-particle interaction force is of the form

$$\mathbf{f}_{ij} = G m_i m_j \frac{(\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^3}, \quad (1)$$

whereas the two-particle potential energy is

$$U_{ij} = -\frac{G m_i m_j}{|\mathbf{r}_j - \mathbf{r}_i|}. \quad (2)$$

The equation of motion of the i th particle then becomes

$$m_i \ddot{\mathbf{r}}_i = \sum_{j \neq i} G m_i m_j \frac{(\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^3}. \quad (3)$$

The total kinetic energy is

$$K = \frac{1}{2} \sum_i \dot{\mathbf{r}}_i \cdot \dot{\mathbf{r}}_i. \quad (4)$$

The total potential energy is

$$U = \frac{1}{2} \sum_{i,j}^{i \neq j} = -\frac{1}{2} \sum_{i,j}^{i \neq j} \frac{G m_i m_j}{|\mathbf{r}_j - \mathbf{r}_i|}, \quad (5)$$

where the factor $1/2$ is to compensate for double counting. We can form the scalar product of (3) with $\dot{\mathbf{r}}_i$, and then sum over all particles, to obtain

$$\sum_i m_i \dot{\mathbf{r}}_i \cdot \ddot{\mathbf{r}}_i = \sum_{i,j}^{j \neq i} G m_i m_j \frac{\dot{\mathbf{r}}_i \cdot (\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^3}, \quad (6)$$

which is equivalent to

$$\frac{1}{2} \frac{d}{dt} \sum_i m_i \dot{\mathbf{r}}_i \cdot \dot{\mathbf{r}}_i = \sum_{i,j}^{j \neq i} G m_i m_j \frac{\dot{\mathbf{r}}_i \cdot (\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^3}, \quad (7)$$

or

$$\frac{dK}{dt} = \sum_{i,j} G m_i m_j \frac{\dot{\mathbf{r}}_i \cdot (\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^3}, \quad (8)$$

where use has been made of (4). Swapping the dummy indices i and j on the right-hand side of the above expression yields

$$\frac{dK}{dt} = \sum_{j,i}^{i \neq j} G m_j m_i \frac{\dot{\mathbf{r}}_j \cdot (\mathbf{r}_i - \mathbf{r}_j)}{|\mathbf{r}_i - \mathbf{r}_j|^3} = - \sum_{i,j}^{j \neq i} G m_i m_j \frac{\dot{\mathbf{r}}_j \cdot (\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^3}. \quad (9)$$

Forming half the sum of the previous two equations, we obtain

$$\frac{dK}{dt} = \sum_{i,j}^{j \neq i} G m_i m_j \frac{(\dot{\mathbf{r}}_i - \dot{\mathbf{r}}_j) \cdot (\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^3} = \frac{1}{2} \frac{d}{dt} \sum_{i,j}^{j \neq i} \frac{G m_i m_j}{|\mathbf{r}_j - \mathbf{r}_i|} = - \frac{dU}{dt}, \quad (10)$$

where use has been made of (5). Hence,

$$\frac{d(K + U)}{dt} = 0, \quad (11)$$

which implies that the total energy of the system, $E = K + U$, is a constant.

2. Suppose that

$$f(t x_1, t x_2, t x_3, \dots) = t^\alpha f(x_1, x_2, x_3, \dots) \quad (12)$$

for all t . It follows that

$$\frac{d}{dt} f(t x_1, t x_2, t x_3, \dots) = \alpha t^{\alpha-1} f(x_1, x_2, x_3, \dots). \quad (13)$$

But, we can also write

$$\frac{d}{dt} f(t x_1, t x_2, t x_3, \dots) = \sum_i x_i \frac{\partial f(t x_1, t x_2, t x_3, \dots)}{\partial (t x_i)}. \quad (14)$$

Hence,

$$\sum_i x_i \frac{\partial f(t x_1, t x_2, t x_3, \dots)}{\partial(t x_i)} = \alpha t^{\alpha-1} f(x_1, x_2, x_3, \dots). \quad (15)$$

Setting $t = 1$, we get

$$\sum_i x_i \frac{\partial f(x_1, x_2, x_3, \dots)}{\partial x_i} = \alpha f(x_1, x_2, x_3, \dots). \quad (16)$$

2.3. Now,

$$\mathbf{f}_{ij} = k_i k_j \frac{(\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^{n+1}} \quad (17)$$

is the appropriate expression for an attractive central two-particle force whose magnitude is $k_i k_j |\mathbf{r}_j - \mathbf{r}_i|^{-n}$. However,

$$k_i k_j \frac{(\mathbf{r}_j - \mathbf{r}_i)}{|\mathbf{r}_j - \mathbf{r}_i|^{n+1}} = -\frac{1}{n-1} \frac{\partial}{\partial \mathbf{r}_i} \left(\frac{k_i k_j}{|\mathbf{r}_j - \mathbf{r}_i|^{n-1}} \right), \quad (18)$$

provided that $n \neq 1$. In other words,

$$\mathbf{f}_{ij} = -\frac{\partial U_{ij}}{\partial \mathbf{r}_i}, \quad (19)$$

where

$$U_{ij} = -\frac{1}{n-1} \frac{k_i k_j}{|\mathbf{r}_j - \mathbf{r}_i|^{n-1}} \quad (20)$$

is the two-particle potential energy. The total potential energy is

$$U = \frac{1}{2} \sum_{i,j}^{i \neq j} U_{ij}. \quad (21)$$

However, if $\mathbf{r}_i \rightarrow t \mathbf{r}_i$ for all i then $U \rightarrow U/t^{n-1}$. Hence, U is a homogeneous function of degree $1 - n$. It follows, from the previous question, that

$$\sum_i \mathbf{r}_i \cdot \frac{\partial U}{\partial \mathbf{r}_i} = -(n-1) U. \quad (22)$$

Now, the equation of motion of the i th particle is

$$m_i \ddot{\mathbf{r}}_i = -\frac{\partial}{\partial \mathbf{r}_i} \sum_{j \neq i} U_{ij} = -\frac{1}{2} \frac{\partial}{\partial \mathbf{r}_i} \sum_{k,j} U_{kj}. \quad (23)$$

The final step follows because only those terms in the sum for which either $j = i$ or $k = i$ survive partial differentiation with respect to \mathbf{r}_i , and also because $U_{ij} = U_{ji}$. Hence, using (21), the equation of motion becomes

$$m_i \ddot{\mathbf{r}}_i = -\frac{\partial U}{\partial \mathbf{r}_i}. \quad (24)$$

Forming the scalar product with \mathbf{r}_i , and summing over all i , we get

$$\sum_i m_i \dot{\mathbf{r}}_i \cdot \ddot{\mathbf{r}}_i = -\sum_i \mathbf{r}_i \cdot \frac{\partial U}{\partial \mathbf{r}_i} = (n-1)U, \quad (25)$$

where use has been made of (22). Now,

$$\sum_i m_i \dot{\mathbf{r}}_i \cdot \ddot{\mathbf{r}}_i = \frac{1}{2} \frac{d^2}{dt^2} \sum_i m_i \mathbf{r}_i \cdot \mathbf{r}_i - \sum_i m_i \dot{\mathbf{r}}_i \cdot \dot{\mathbf{r}}_i, \quad (26)$$

which yields

$$\sum_i m_i \dot{\mathbf{r}}_i \cdot \ddot{\mathbf{r}}_i = \frac{1}{2} \ddot{I} - 2K. \quad (27)$$

So, from (25),

$$\frac{1}{2} \ddot{I} = 2K + (n-1)U. \quad (28)$$

Now, in a steady state, $\ddot{I} = 0$, so that

$$U = -\frac{2K}{n-1}. \quad (29)$$

In this case, the total energy becomes

$$E = K + U = \left(\frac{n-3}{n-1} \right) K. \quad (30)$$

We need $E < 0$ for a bound state (assuming $n > 1$, so that $U \rightarrow 0$ as the system disperses to infinity). Hence, we need

$$n < 3. \quad (31)$$

In other words, there are no bound steady states for $n > 3$.

4. The virial equation, (28), for a gravitationally bound (*i.e.*, $n = 2$) system, can be written

$$\frac{1}{2} \ddot{I} = 2K + U = 2(K + U) - U. \quad (32)$$

However, the total energy, $E = K + U$, of an isolated system is constant in time. Hence, the above equation becomes

$$\ddot{I} = -2U + c, \quad (33)$$

where $c = 4E$ is a constant. Suppose that the system expands radially, in a uniform fashion, by some factor $1 + u(t)$. If R is the outer radius of the star, and M its total mass, then $I \propto M R^2$ and $U \propto G M/R$. Hence, if $R \rightarrow R(1 + u)$ at constant mass then $I \rightarrow I_0(1 + u)^2$ and $U \rightarrow U_0/(1 + u)$, where I_0 and U_0 are the unperturbed (*i.e.*, $u = 0$) moment of inertia and potential energy, respectively. It follows from (33) that, in the unperturbed (*i.e.*, $d/dt = 0$) state,

$$0 = -2U_0 + c. \quad (34)$$

Hence, (33) gives

$$\frac{d^2}{dt^2}[I_0(1 + u)^2] = -2U_0/(1 + u) + c. \quad (35)$$

Assuming that $|u| \ll 1$, so that the radial oscillations are of relatively small amplitude, we get

$$2I_0 \frac{d^2 u}{dt^2} \simeq -2U_0 + c + 2U_0 u = -2|U_0| u, \quad (36)$$

where use has been made of (34) and the fact that $U_0 < 0$. Hence, the radial oscillation equation takes the form

$$\frac{d^2 u}{dt^2} = -\frac{|U_0|}{I_0} u. \quad (37)$$

Fitzpatrick, Chapter 2

Exercise 2.5

All the particles have the same charge-to-mass ratio:

$$\frac{q_i}{m_i} = \frac{q}{m}$$

If the system is in a uniform magnetic field \vec{B} , the equation of motion for the i^{th} particle is

$$m_i \ddot{\vec{r}}_i = \sum_{j \neq i} \frac{k q_i q_j}{|\vec{r}_i - \vec{r}_j|^3} (\vec{r}_i - \vec{r}_j) + q_i \dot{\vec{r}}_i \times \vec{B}$$

If we sum over i , the left side is the time derivative of the total momentum

$$\sum_i m_i \ddot{\vec{r}}_i = \frac{d}{dt} \left(\sum_i m_i \dot{\vec{r}}_i \right) = \frac{d}{dt} \vec{P}$$

The resulting equation can be written

$$\begin{aligned} \frac{d}{dt} \vec{P} &= \sum_i \sum_{j \neq i} \frac{k q_i q_j}{|\vec{r}_i - \vec{r}_j|^3} (\vec{r}_i - \vec{r}_j) + \sum_i q_i \dot{\vec{r}}_i \times \vec{B} \\ &= \sum_i \sum_{\substack{j \\ i \neq j}} \frac{k q_i q_j}{|\vec{r}_i - \vec{r}_j|^3} \frac{1}{2} [(\vec{r}_i - \vec{r}_j) + (\vec{r}_j - \vec{r}_i)] + \left(\sum_i q_i \dot{\vec{r}}_i \right) \times \vec{B} \\ &= \frac{q}{m} \vec{P} \times \vec{B} \end{aligned}$$

This equation can be written

$$\frac{d\vec{P}}{dt} = -\Omega \hat{B} \times \vec{P},$$

$$\Omega = \frac{q}{m} B$$

It implies that \vec{P} precesses around the direction \hat{B} with angular frequency Ω .

The total angular momentum parallel to \vec{B} is

$$\begin{aligned} L_{\parallel} &= \vec{L} \cdot \hat{B} \\ &= \left(\sum_i m_i \vec{r}_i \times \dot{\vec{r}}_i \right) \cdot \hat{B} \end{aligned}$$

The moment of inertia about an axis through the origin parallel to \hat{B} is

$$I_{\parallel} = \sum_i m_i (\vec{r}_i \times \hat{B})^2$$

The time derivative of L_{\parallel} is

$$\begin{aligned} \frac{d}{dt} L_{\parallel} &= \left[\sum_i m_i (\dot{\vec{r}}_i \times \hat{B} + \vec{r}_i \times \ddot{\vec{r}}_i) \right] \cdot \hat{B} \\ &= \left(\sum_i \vec{r}_i \times (m_i \ddot{\vec{r}}_i) \right) \cdot \hat{B} \end{aligned}$$

Inserting the equations of motion, this becomes

$$\begin{aligned} \frac{d}{dt} L_{\parallel} &= \left(\sum_i \vec{r}_i \times (q_i \dot{\vec{r}}_i \times \vec{B}) \right) \cdot \hat{B} \\ &= \sum_i q_i (\dot{\vec{r}}_i \times \vec{B}) \times \vec{r}_i \cdot \hat{B} \\ &= -\frac{q}{m} B \sum_i m_i (\dot{\vec{r}}_i \times \hat{B}) \cdot (\vec{r}_i \times \vec{B}) \end{aligned}$$

The time derivative of I_{\parallel} is

$$\frac{d}{dt} I_{\parallel} = \sum_i m_i 2 (\vec{r}_i \times \hat{B}) \cdot (\dot{\vec{r}}_i \times \vec{B})$$

Thus the time derivative of $L_{\parallel} + \frac{1}{2} \Omega I_{\parallel}$ is

$$\begin{aligned} \frac{d}{dt} (L_{\parallel} + \frac{1}{2} \Omega I_{\parallel}) &= -\frac{q}{m} B \sum_i m_i (\dot{\vec{r}}_i \times \hat{B}) \cdot (\vec{r}_i \times \vec{B}) \\ &\quad + \frac{1}{2} \left(\frac{q}{m} B \right) 2 \sum_i m_i (\vec{r}_i \times \hat{B}) \cdot (\dot{\vec{r}}_i \times \vec{B}) \\ &= 0 \end{aligned}$$

Thus $L_{\parallel} + \frac{1}{2} \Omega I_{\parallel}$ is a constant of the motion.